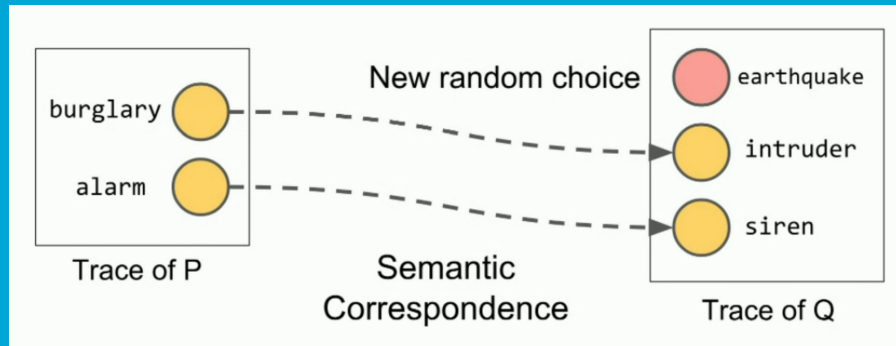


Incremental Inference for Probabilistic Programs

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Contributions of the paper

What?

A novel approach for approximate sampling based on incremental inference

Why?

Avoid expensive sampling computation by sampling from a **known** program

How?

Adapt traces from one program to another using a *Trace translator*

Optimise adapted traces (*samples*) using sequential Monte Carlo

Incremental inference

Given two probabilistic programs P and Q , and samples of P obtained using an existing inference algorithm, generate samples for Q by leveraging the samples for P .

- Construct a *trace translator* to adapt samples of P into samples of Q
- Compute *weights* for the adapted traces and reweight like in SMC
- Optionally perform *resampling* proportional to the computed weights
- Use *MCMC sampling* intermittently to increase approximation quality
- The generated output traces store all the inferred properties

Applications

When?

- When the posterior distributions of the programs are “close enough”
- When the programs are variants of the same model
- When the data the models are conditioned on is changed
- When the prior assumptions of the models are changed
- When model changes originate from an automated process

Else?

- Proceed with standard non-incremental inference
- Use the available traces to warm-start samplers like MCMC ?

Applications

When?

- When the posterior distributions of the programs are “close enough”
- When the programs are variants of the same model

Why not always use MCMC with the available traces?

- when the prior assumptions of the models are changed

**Traces might contain different number of random choices.
MCMC is less efficient when programs are very similar.**

- Use the available traces to warm-start samplers like MCMC ?

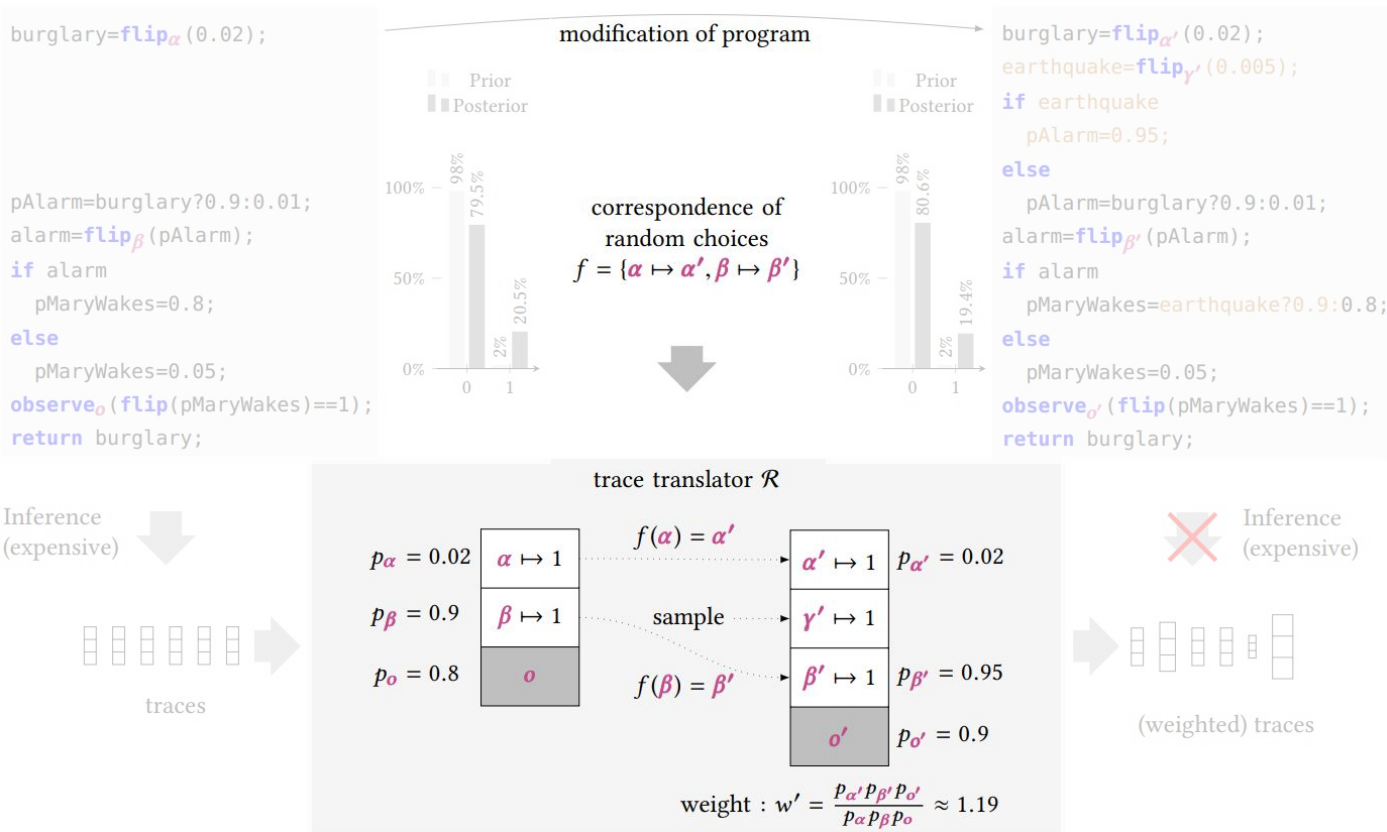
Getting technical

Incremental inference

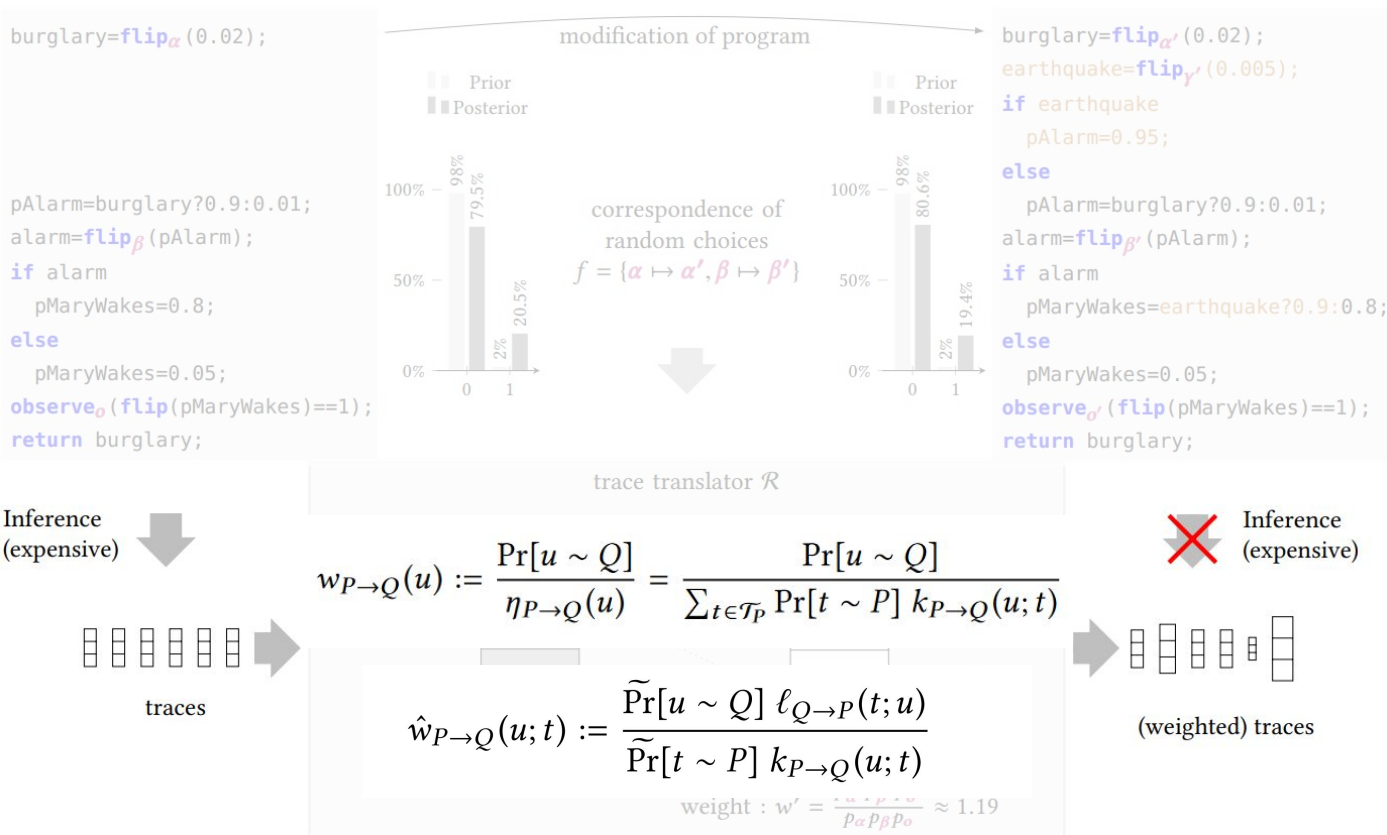
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- Construct a **trace translator** to adapt samples of P into samples of Q



- Compute **weights** for the adapted traces and reweight like in SMC



Incremental inference

Given two probabilistic programs P and Q , and samples of P obtained using an existing inference algorithm, generate samples for Q by leveraging the samples for P .

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Incremental inference

Given two probabilistic programs P and Q , and samples of P obtained using an existing inference algorithm, generate samples for Q by leveraging the samples for P

Why can we use MCMC sampling here, but not before?

We apply MCMC to valid traces for target program Q

- Use **MCMC sampling** intermittently to increase approximation quality
- The generated output traces store all the inferred properties

Implementation

Step-by-Step

1. Establish correspondence function \mathbf{f} between variables
2. Initialize P-score and Q-score to 0 (for weighting)
3. Run target program \mathbf{Q} once to obtain trace \mathbf{u}
4. For every variable in \mathbf{u} , and every available trace \mathbf{t} :
 - a. Is the variable in trace \mathbf{t} ?
 - i. **Yes?** Take the value from \mathbf{t} .
Increase Q-score by log probability of corresponding choice in \mathbf{Q}
 - ii. **No?** Sample a new value from the prior of \mathbf{Q} .
 - b. Is this an observation?
 - i. Increase Q-score by log probability of observation
5. P-score = sum of log probabilities of choices and observations of \mathbf{t}
6. Log weight = P-score - Q-score

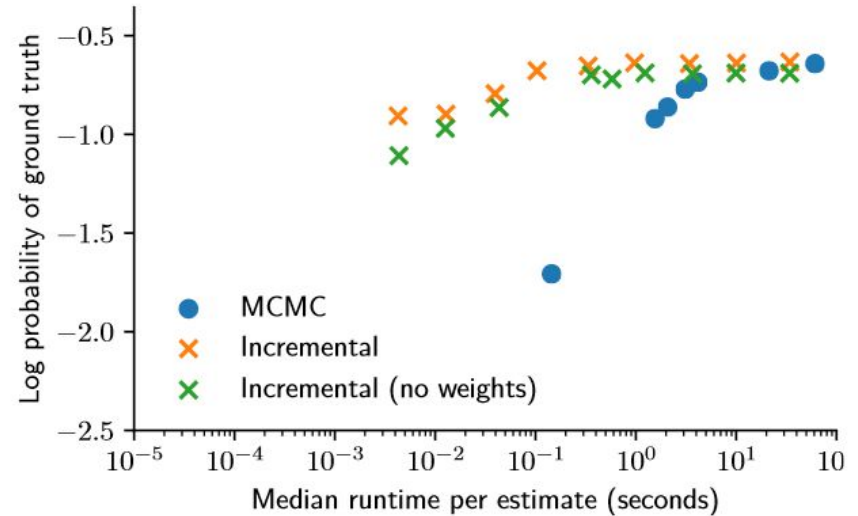
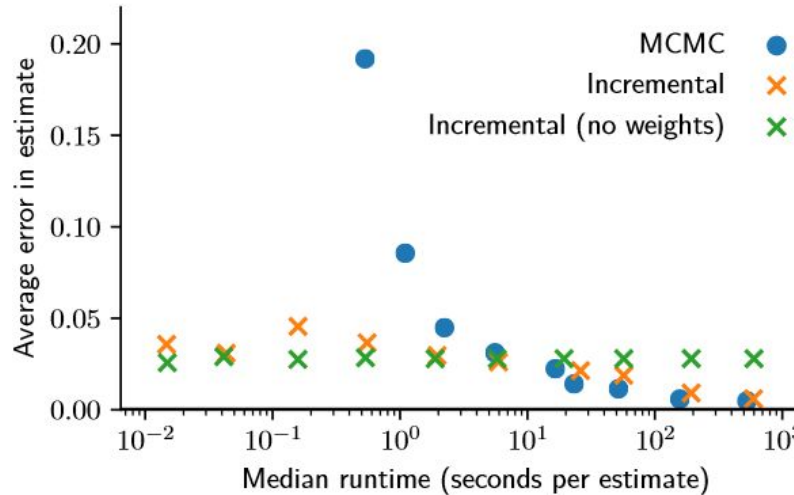
$$\hat{w}_{P \rightarrow Q}(u; t) := \frac{\tilde{\text{Pr}}[u \sim Q] \ell_{Q \rightarrow P}(t; u)}{\tilde{\text{Pr}}[t \sim P] k_{P \rightarrow Q}(u; t)}$$

Recap

1. Establish variable correspondences
2. Collect traces \mathbf{t} from original program \mathbf{P}
3. Translate traces \mathbf{t} to traces \mathbf{u} in target program \mathbf{Q}
4. Calculate weights for each step
5. Resample traces \mathbf{u} according to weight (Optional)
6. Apply MCMC to traces \mathbf{u} to improve their quality

The experiments
(were bad)

Experimental results



Questions?