# Hamiltonian dynamics for sampling

Var burglary = sample(Bernoulli(0.1))

Var burglary = sample(Bernoulli(0.1))

Var somethingDifficult = sample(Complex(1,3))

# What to do now?

- Enumeration
- Rejection sampling
- Importance sampling
- MCMC
- Particle filtering

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- Will find the left peak eventually
- Will find the right peak when given even more time



# Some physics: Hamiltonian

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$$\frac{dp}{dt} = -\frac{dH}{dq}$$
$$\frac{dq}{dt} = \frac{dH}{dp}$$

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```
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```

- 1. Conservation of energy, the Hamiltonian
- 2. Reversibility
- 3. Volume conservation



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• We use U for our target, U=-In(f(q))

$$P(q,p) = \frac{f(q)}{Z} \exp\left(-\frac{p^2}{2}\right)$$

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![](_page_19_Figure_1.jpeg)

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Thus: we skip a slow random walk

#### Some example performance

$$H(q, p) = q^T \Sigma^{-1} q / 2 + p^T p / 2, \quad \text{with} \quad \Sigma = \begin{bmatrix} 1 & 0.95 \\ 0.95 & 1 \end{bmatrix}$$

![](_page_20_Figure_2.jpeg)

Figure 3: A trajectory for a 2D Gaussian distribution, simulated using 25 leapfrog steps with a stepsize of 0.25. The ellipses plotted are one standard deviation from the means. The initial state had  $q = [-1.50, -1.55]^T$  and  $p = [-1, 1]^T$ .